Jingwen YU 于靖文

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Education

The Hong Kong University of Science and Technology — Hong Kong SAR, China
Ph.D. in Electronic and Computer Engineering — *Sep. 2021 – Present*

- Supervisors: **Prof. Ping TAN** and **Chair Prof. Hong ZHANG (SUSTech)**
- Affiliation: CKS-Robotics Institute, Shenzhen Key Laboratory of Robotics and Computer Vision
- Research interests: Loop Closure Detection, Visual Place Recognition, Visual Localization, Visual Navigation

Southern University of Science and Technology (Magna Cum Laude) — Shenzhen, China
B.Eng. in Electronic and Electrical Engineering **GPA: 3.89/4.0** — *Sep. 2017 – Jun. 2021*

- Supervision: **Chair Prof. Hong ZHANG**

National University of Singapore — Singapore
Visiting Student in School of Computing (SoC) — *Jun. 2019 - Aug. 2019*

High School Attached To Shandong Normal University — Jinan, China
Sep. 2014 - Jun. 2017

Research Experience

Geometric Verification of Loop Closure Detection (*IROS 2024*) — *Sep. 2023 – Present*

- GV-Bench: Benchmarking Local Feature Matching for Geometric Verification

Multi-Sensor Fusion SLAM (*IROS 2022*, *Arxiv 2024*) — *Sep. 2021 – Present*

- Explore the multi-sensor localization system on the quadruped robot.
- Benchmarking multi-sensor fusion SLAM by collecting a multi-platform SLAM dataset.

Semantic Scene Understanding for manipulation (*IROS 2022*) — *Jun. 2021 – Mar. 2022*

- Explore relationship-oriented scene understanding for robotic manipulation.

Conditional-invariant Visual Place Recognition (*Robotica 2023*) — *Feb. 2021 – Aug. 2021*

- Employ convolutional autoencoder to generate conditional-invariant image global descriptor.

Publications

[1] **J. Yu**, H. Ye, J. Jiao, P. Tan, H. Zhang, "GV-Bench: Benchmarking Local Feature Matching for Geometric Verification of Long-term Loop Closure Detection," ***IROS***, 2024.

[2] H. Wei, J. Jiao, X. Hu, **J. Yu**, X. Xie, J. Wu, Y. Zhu, Y. Liu, L. Wang, M. Liu, "FusionPortableV2: A Unified Multi-Sensor Dataset for Generalized SLAM Across Diverse Platforms and Scalable Environments," ***Arxiv Preprint***, 2024.

[3] W. Chen, D. Huang, Y. Pan, G. Chen, J. Ruan, **J. Yu**, J. Zheng, H. Zhang, "Cloud Learning-based Meets Edge Model-based: Robots Don't Need to Build All the Submaps Itself," ***IEEE Transactions on Vehicular Technology***, 2023.

[4] H. Ye, W. Chen, **J. Yu**, L. He, Y. Guan, H. Zhang, "Condition-invariant and compact visual place description by convolutional autoencoder," ***Robotica***, 2023.

[5] C. Tang, **J. Yu**, W. Chen, B. Xia, H. Zhang, "Relationship Oriented Semantic Scene Understanding for Daily Manipulation Tasks," ***IROS***, 2022.

[6] J. Jiao, H. Wei, T. Hu, X. Hu, Y. Zhu, Z. He, J. Wu, **J. Yu**, X. Xie, H. Huang, R. Geng, L. Wang, M. Liu, "Fusionportable: A multi-sensor campus-scene dataset for evaluation of localization and mapping accuracy on diverse platforms," ***IROS***, 2022.

Projects & Working experience

Autonomous Shuttle Vehicle on Campus *Dec. 2023 – Dec. 2024* (**SUSTech**)

(**Project Leader**) This project aims to expand the limits of vision-based navigation by implementing a teach-and-repeat (T&R) navigation system on a real-world autonomous shuttle vehicle on campus. This project is partially supported by the undergraduate "Climbing" research program of Guangdong Province.

Cloud-Edge Collaborated Visual SLAM System *Apr. 2022 – Nov. 2023* (**SUSTech**)

This project aims at developing a visual simultaneous localization and mapping (VSLAM) system to efficiently leverage cloud and onboard computing resources (please check IEEE TVT paper). I proposed and implemented an adaptive frame downsampling method to optimize communication transmission bandwidth.

Trials of the Autonomous Logistic Vehicle (Hercules) *Sep. 2021 – Aug. 2023* (**HKUST**)

This project aims at deploying an autonomous logistic vehicle (please check IEEE RAM paper) in HKUST to deliver food and goods between restaurants and offices. My role in this project is to conduct a series of tests on the campus to demonstrate that the autonomous vehicle (Hercules) is safe, reliable, and intelligent.

UGV-Quadrupedal Robot Autonomous Delivery *Sep. 2021 – Aug. 2022* (**HKUST**)

(**Core Participator**) This project aims at deploying a quadrupedal robot for indoor "last mile" delivery in collaboration with an autonomous logistic vehicle on the HKUST campus. I implemented an indoor LIDAR-inertial localization system on a quadrupedal robot (Unitree A1). Real-world experiments have been conducted in the Cheng Yu Tung Building (CYT) and Robotics Institute (RI) of HKUST.

Undergraduate Teaching Assitant *Jan. 2021 – Jun. 2021* (**SUSTech**)

EE346 Mobile Robot Navigation

Graduate Teaching Assitant *Jan. 2022 – Dec. 2022* (**HKUST**)

ELEC3120 Computer Communication Network

Research Assitant *Jun. 2021 – Sep. 2021* (**SUSTech**)

Shenzhen Key Laboratory of Robotics and Computer Vision

Awards & Achievements

China National Scholarship (0.2% Nationwide) *Oct. 2020* (Ministry of Education, China)

First Class of the Merit Student Scholarship *Oct. 2018* & *Oct. 2019* (SUSTech)

Admission Scholarship *Oct. 2017* (SUSTech)

Shenzhen Outstanding Student Leader *Jan. 2020* (Guangdong Students' Federation)

Services

Reviewer of IEEE/RSJ IROS2024, IEEE ICRA2024, IEEE IV 2023, 2022

IEEE ICRA 2021 Organizing Committee & Outstanding Volunteer

MICCAI 2018 Volunteer

Last update on Aug 2^{nd}, 2024